

Introduction

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Aim : model the progression of Parkinson's disease

Tools and Data

- Gain understanding the progression of Parkinson's disease
 - Infer a template of the average disease progression
- Infer each patient disease stage and future evolution
 - Two individuals at the same age might be at different stages of disease progression
 - Age is modeled as a random variable and not a covariable

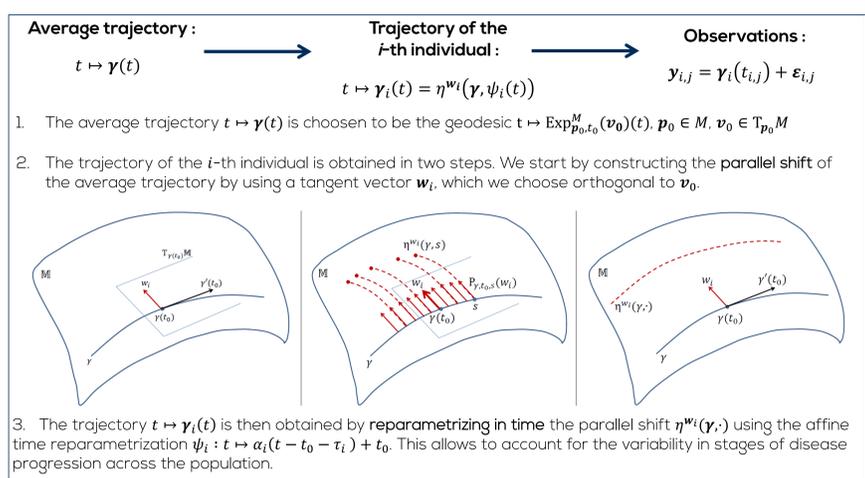
- We use a non linear mixed-effect model to estimate the temporal progression of the biomarkers
- We use multimodal data regrouping cognitive scores, motor scores and imaging from the international PPMI cohort on Parkinson's Disease.

Methods

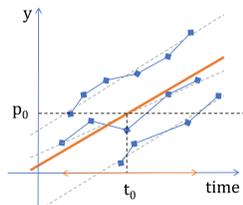
Generic spatio-temporal model for longitudinal data

Summary : we use a generic mixed-effects model for longitudinal manifold-valued data [Schiratti et al, 2015]. The model allows to estimate an average trajectory as well as individual trajectories. Random effects characterize changes in direction and pace at which individual trajectories are followed. This generic model is used to analyze the temporal progression of a family of univariate biomarkers.

➤ A hierarchical model :



- $(\tilde{M}, g^{\tilde{M}})$ smooth Riemannian manifold included in \mathbf{R}^n
- (M, g^M) sub-Riemannian manifold of \tilde{M} , assumed to be geodesically complete
- $p \in M$, $v \in T_pM$, $\text{Exp}_p^M(v)$: Riemannian exponential in M at p of the tangent vector v
- $\gamma : \mathbf{R} \rightarrow M$: geodesic of M
- $t, t_0 \in \mathbf{R}$, $P_{\gamma, t_0, t}(\cdot)$: parallel transport in M along γ from $\gamma(t_0)$ to $\gamma(t)$.
- $t \mapsto \text{Exp}_{p, t_0}^M(v)(t)$: geodesic of M which goes through p at time t_0 with velocity v .



The model in practice for scalar longitudinal data

Univariate Linear Model

$M = \mathbb{R}$ (equipped with canonical metric)

$$y_{i,j} = p_0 + \alpha_i v_0(t_{i,j} - t_0 - \tau_i) + \epsilon_{i,j}$$

Univariate Logistic Model

$M =]0,1[$ with the metric $g = (g_p)_{p \in]0,1[}$, $g_p(u, v) = uv/p^2(1-p)^2$

$$y_{i,j} = \left(1 + \left(\frac{1}{p_0} - 1\right) \exp\left(\frac{-\alpha_i v_0(t_{i,j} - t_0 - \tau_i)}{p_0(1-p_0)}\right)\right)^{-1} + \epsilon_{i,j}$$

Aim : Analyze the temporal progression of a family of N biomarkers.

- We assume that the measurements of each biomarker belong to a one-dimensional Riemannian manifold I , geodesically complete and included in \mathbf{R} . As a consequence, M is a product of one-dimensional manifolds : $M = I^N = I \times I \times \dots \times I$.
- The average trajectory $t \mapsto \gamma(t)$ is chosen among a parametric family of geodesics of M : $\gamma(t) = (\gamma_0(t), \gamma_1(t), \dots, \gamma_{N-1}(t))$

Multivariate Linear Model

$$y_{i,j,k} = p_k + v_k \alpha_i(t_{i,j,k} - t_0 - \tau_i) + (A s_i)_k + \epsilon_{i,j,k}$$

Multivariate Logistic Model

$$y_{i,j,k} = \left(1 + \left(\frac{1}{p_k} - 1\right) \exp\left(\frac{-\alpha_i v_k(t_{i,j,k} - t_0 - \tau_i) + (A s_i)_k}{p_k(1-p_k)}\right)\right)^{-1} + \epsilon_{i,j,k}$$

- Missing values can be discarded as we have a generative model

Estimation of model parameters

The parameters of the generic spatio-temporal model are $\theta = (p, t_0, v, \sigma_\epsilon, \sigma, \text{vec}(A))$.

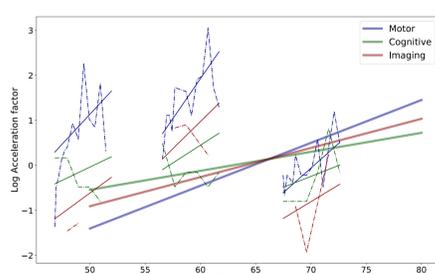
➤ Overview of the MCMC-SAEM for the multivariate logistic model :

$z^{(p)}$ (resp. $\theta^{(p)}$) denotes the vector of hidden variables (resp. parameters) at the p -th iteration.

- Initialisation : $\theta \leftarrow \theta^{(0)}$, $z^{(0)} \leftarrow \text{random}$, $S \leftarrow 0$, $(\epsilon_p)_p$ sequence of positive step-sizes
- repeat until convergence
- Simulation (Hasting-Metropolis within Gibbs sampler) : $z^{(p+1)} \leftarrow \text{Gibbs sampler}(z^{(p)}, y, \theta^{(p)})$
- Compute the sufficient statistics : $S_1^{(p)} \leftarrow [y_{i,j}^{(p)T} f_{i,j}]_{i,j}$, $S_2^{(p)} \leftarrow [\|f_{i,j}\|_2^2]_{i,j}$, $S_3^{(p)}, S_4^{(p)} \leftarrow [(\xi_i^{(p)})]_i, [(\tau_i^{(p)})]_i$, $S_5^{(p)}, S_6^{(p)}, S_7^{(p)}, S_8^{(p)} \leftarrow p_0^{(p)}, t_0^{(p)}, v_0^{(p)}, [\beta_j^{(p)}]_j$
- Stochastic approximation : $S_j^{(p+1)} \leftarrow S_j^{(p)} + \epsilon_k (S_j(z^{(p)}) - S_j^{(p)})$ for all j
- Maximization ($\theta^{(k+1)} \leftarrow \text{argmax}_{\theta \in \Theta} [-\phi(\theta) + (S^{(p+1)}, \psi(\theta))]$) : closed-form updates
- end repeat

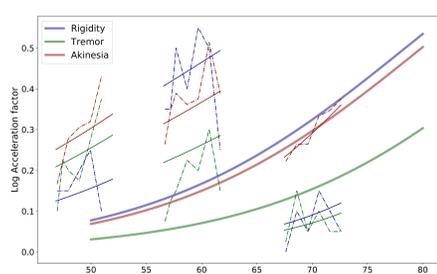
Results

Multivariate Linear Model



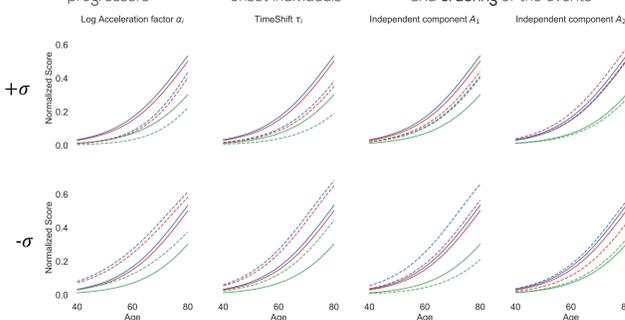
Multivariate linear model for motor, cognitive and imaging scores. In wide the mean template of the model, and for 3 patients the model and real scores respectively in plain and dotted lines.

Multivariate Logistic Model



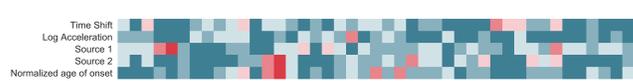
Multivariate logistic model for 3 different motor score linked with the MDS-UPDRS normalized between 0 and 1. In wide the mean template of the model, and for 3 patients the model and real scores respectively in plain and dotted lines.

Distinguish fast vs slow progressors, Distinguish early vs late onset individuals, Variability in the relative timing and ordering of the events

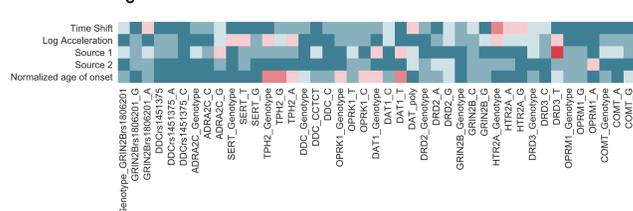


Right: The figure illustrates the effect of the variance of the acceleration factors, and the two estimated independent components ($N_s = 2$). Individual space shifts along the first (or second) independent components may change the relative order between the motor modalities.

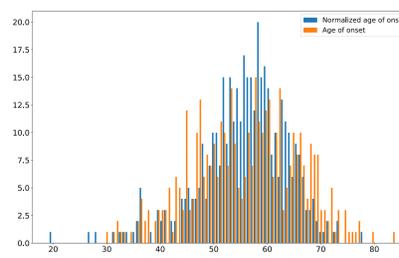
Multivariate Linear Model



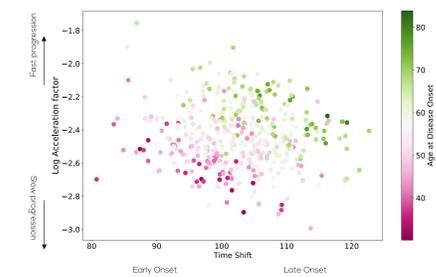
Multivariate Logistic Model



Left : Correlation between both computed models and gene data. We seek to find correlations between covariables of interest and model output to gain understanding of the disease.



Histogram of the ages of conversion to PD (t_i^{conv}) in orange and histogram of the normalized ages ($(\psi_i(t_i^{\text{conv}}))_i$) ; ages of conversion mapped from the individual timeline to the reference timeline using the subject-specific affine reparametrization.



Plot of temporal individual parameters against the age of conversion to PD. The Time shifts correlates well with the age of conversion ($\rho = 0.6$).

Conclusion

We use a mixed-effect model which is able to evaluate a group-average spatiotemporal propagation of biomarkers. Moreover, individual parameters characterizing personalized patterns of propagation as variations of the mean scenario are estimated. The evaluation of this model is made with the MCMC-SAEM algorithm. Applied on Parkinson's disease, we model a mean template of the disease evolution, while being customizable to fit individual data, predicting stage of the disease or time to symptom onset. We wish now to use this information to be able to correlate the model output with covariables of interest such as gene data, and separate patients in distinct clusters characterizing different subtypes of the disease.

References

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